



THE UNIVERSITY OF TEXAS AT AUSTIN

Department of Statistics and Data Sciences

College of Natural Sciences

SDS 321: Introduction to Probability and Statistics

Lecture 12: Independence of discrete random variables and Continuous random variables

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Conditional PMF: summary

- ▶ Conditional PMF is exactly like conditional probabilities. Your new sample space is one where the conditioning event has taken place.

- ▶ By definition, we have $P(X = x|Y = y) = \frac{P(X = x, Y = y)}{P(Y = y)}$, where $P(Y = y) > 0$.

- ▶ $\sum_x P(X = x|Y = y) = 1$.

- ▶ The multiplication rule:

- ▶ $P(X = x, Y = y) = P(X = x|Y = y)P(Y = y)$.

- ▶ For 3 random variables, $P(X = x, Y = y, Z = z)$ equals $P(X = x|Y = y, Z = z)P(Y = y|Z = z)P(Z = z)$

- ▶ Total probability rule:

$$P(X = x) = \sum_y P(X = x, Y = y) = \sum_y P(X = x|Y = y)P(Y = y).$$

Conditional Expectation

- ▶ Recall the **expectation** of X . $E[X] = \sum_x xP(X = x)$.
- ▶ The **conditional expectation** of random variable X given event A with $P(A) > 0$ is defined as: $E[X|A] = \sum_x xP(X = x|A)$.
- ▶ For a function $g(X)$, $E[g(X)|A] = \sum_x g(x)P(X = x|A)$.
- ▶ The conditional expectation of X given $Y = y$ is given by $E[X|Y = y] = \sum_x xP(X = x|Y = y)$.
- ▶ How are $E[X|Y = y]$ related to $E[X]$?
—**Total expectation theorem!**

Total expectation theorem

► We have $E[X|Y = y]P(Y = y) = \sum_x xP(X = x|Y = y)P(Y = y)$

Total expectation theorem

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$$E[X|Y = y]P(Y = y) = \sum_x xP(X = x|Y = y)P(Y = y)$$
$$\sum_y E[X|Y = y]P(Y = y) = \sum_y \sum_x xP(X = x|Y = y)P(Y = y)$$
$$\sum_y E[X|Y = y]P(Y = y) = \sum_y \sum_x x \underbrace{P(X = x|Y = y)P(Y = y)}_{P(X=x, Y=y)}$$

Total expectation theorem

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$$= \sum_x x \underbrace{\sum_y P(X = x|Y = y)P(Y = y)}_{P(X=x)}$$
$$= \sum_x xP(X = x)$$

Total expectation theorem

► We have

$$\begin{aligned} E[X|Y = y]P(Y = y) &= \sum_x xP(X = x|Y = y)P(Y = y) \\ \sum_y E[X|Y = y]P(Y = y) &= \sum_y \sum_x xP(X = x|Y = y)P(Y = y) \\ \sum_y E[X|Y = y]P(Y = y) &= \sum_y \sum_x x \underbrace{P(X = x|Y = y)P(Y = y)}_{P(X=x, Y=y)} \\ &= \sum_x x \underbrace{\sum_y P(X = x|Y = y)P(Y = y)}_{P(X=x)} \\ &= \sum_x xP(X = x) \\ &= E[X] \end{aligned}$$

- So $E[X]$ is just a weighted average of $E[X|Y = y]$, the weights being the probability of $Y = y$.

Roadmap - discrete r.v. - independence

- ▶ Independence of two events
- ▶ Independence of a random variable and an event
- ▶ Independence of two random variables—pairwise independence
 - ▶ Implications – expectation of the product of two independent r.v.'s
 - ▶ Implications – variance of the sum of two independent r.v.'s
- ▶ Generalization to multiple random variables
 - ▶ Implication – variance of a binomial
- ▶ Conditional independence

Independence of random variables

- ▶ Lets first consider two events $\{X = x\}$ and A . We know that these two events are independent if $P(\{X = x\}, A) = P(\{X = x\})P(A)$
- ▶ In other words if $P(A) > 0$, then $P(X = x|A) = P(X = x)$, i.e. knowing the occurrence of A does not change our belief about $\{X = x\}$.
- ▶ We will call the random variable X and event A to be independent if

$$P(X = x, A) = P(X = x)P(A) \quad \text{For all } x$$

- ▶ Two random variables are said to be independent if

$$P(X = x, Y = y) = P(X = x)P(Y = y) \quad \text{For all } x \text{ and } y$$

- ▶ To put it a bit differently,

$$P(X = x|Y = y) = P(X = x) \quad \text{For all } x \text{ and } y \text{ such that } P(Y = y) > 0$$

A super important implication

We saw that $E[X + Y] = E[X] + E[Y]$ no matter whether X and Y are independent or not.

- ▶ If X and Y are independent, $E[XY] = E[X]E[Y]$

- ▶
$$E[XY] = \sum_{x,y} xyP(X = x, Y = y) = \sum_{x,y} xyP(X = x)P(Y = y)$$
$$= \left(\sum_x xP(X = x) \right) \left(\sum_y yP(Y = y) \right) = E[X]E[Y]$$

- ▶ In fact, $E[g(X)h(Y)] = E[g(X)]E[h(Y)]$

Variance of sum of independent random variables

Let X and Y be two independent random variables. What is $\text{var}(X + Y)$?

- ▶ Remember! $\text{var}(X + Y) = E[(X + Y)^2] - (E[X + Y])^2$
- ▶
$$\begin{aligned} E[(X + Y)^2] &= E[X^2 + Y^2 + 2XY] = E[X^2] + E[Y^2] + 2E[XY] \\ &= E[X^2] + E[Y^2] + 2E[X]E[Y] \end{aligned}$$

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$$= E[X^2] + E[Y^2] + 2E[X]E[Y]$$

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$$\begin{aligned} \text{var}(X + Y) &= E[(X + Y)^2] - (E[X + Y])^2 \\ &= \underbrace{E[X^2] - E[X]^2}_{\text{var}(X)} + \underbrace{E[Y^2] - E[Y]^2}_{\text{var}(Y)} = \text{var}(X) + \text{var}(Y) \end{aligned}$$

- ▶ Variance of sum of independent random variables equals the sum of the variances!

Independence of several random variables

- ▶ Three random variables X , Y and Z are said to be independent if

$$P(X = x, Y = y, Z = z) = P(X = x)P(Y = y)P(Z = z) \quad \text{For all } x, y, z$$

- ▶ If X , Y , Z are independent, then so are $f(X)$, $g(Y)$ and $h(Z)$.
- ▶ Also, any random variable $f(X, Y)$ and $g(Z)$ are independent.
- ▶ Are $f(X, Y)$ and $g(Y, Z)$ independent?

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- ▶ Are $f(X, Y)$ and $g(Y, Z)$ independent?
 - ▶ **Not necessarily, both have Y in common.**
- ▶ For n independent random variables, X_1, X_2, \dots, X_n , we also have:

$$\text{var}(X_1 + X_2 + X_3 + \dots + X_n) = \text{var}(X_1) + \text{var}(X_2) + \dots + \text{var}(X_n)$$

Variance of a Binomial

Consider n independent Bernoulli variables X_1, X_2, \dots, X_n , each with probability p of having value “1”. The sum $Y = \sum_i X_i$ is a *Binomial*(n, p) random variable.

- ▶ We saw last time that $E[Y] = \sum_i E[X_i] = np$. What about the variance?
- ▶ Recall that $\text{var}(X_i) = p(1 - p)$ for $i \in \{1, 2, \dots, n\}$.
- ▶ $\text{var}(Y) = \text{var}(X_1 + X_2 + \dots + X_n) = \sum_{i=1}^n \text{var}(X_i) = np(1 - p)$.

Conditional Independence

- ▶ Very similar to conditional independence of events!
- ▶ X and Y are conditionally independent, given a positive probability event A if

$$P(X = x, Y = y|A) = P(X = x|A)P(Y = y|A) \quad \text{For all } x \text{ and } y$$

- ▶ Same as saying $P(X = x|Y = y, A) = P(X = x|A)$, i.e.
- ▶ Once you know that A has occurred, knowing $\{Y = y\}$ has occurred does not give you any more information!
- ▶ Like we learned before, conditional independence does not imply unconditional independence.

Example-conditionally independent but not marginally

- ▶ I separately phone two students (Alice and Bob) and tell them the midterm grade.
- ▶ To each, I report the same grade, $G \in \{A+, A..., C\}$.
- ▶ The signal is bad and, Alice and Bob each independently make an educated guess of what I said.
- ▶ Let the grades guessed by Alice and Bob be X and Y .
- ▶ Are X and Y marginally independent?

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 - ▶ **NO.** you would think, $P(X = A|Y = A) > P(X = A)$.

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- ▶ What if I tell you that $G = A-$?

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 - ▶ **NO.** you would think, $P(X = A|Y = A) > P(X = A)$.
- ▶ What if I tell you that $G = A-$?
 - ▶ Are X and Y conditionally independent given $\{G = A\}$.
 - ▶ **YES!** Because if we know the grade I actually said, the two variables are no longer dependent.

Example-marginally independent but not conditionally

- ▶ I toss two dice independently and X and Y are the readings on them.
- ▶ Are X and Y independent?
- ▶ Now I tell you that $X + Y = 12$. Are they still independent?

Cumulative distribution function

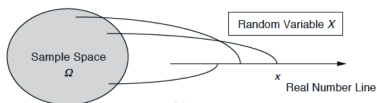
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Roadmap

- ▶ Discrete vs continuous random variables
- ▶ Probability mass function vs Probability density function
 - ▶ Properties of the pdf
- ▶ Cumulative distribution function
 - ▶ Properties of the cdf
- ▶ Expectation, variance and properties
- ▶ The normal distribution

Review: Random variables

A random variable is mapping from the sample space Ω into the real numbers.



So far, we've looked at **discrete random variables**, that can take a finite, or at most countably infinite, number of values, e.g.

- ▶ Bernoulli random variable – can take on values in $\{0, 1\}$.
- ▶ Binomial(n, p) random variable – can take on values in $\{0, 1, \dots, n\}$.
- ▶ Geometric(p) random variable – can take on any positive integer.

Continuous random variable

A **continuous** random variable is a random variable that:

- ▶ Can take on an uncountably infinite range of values.
- ▶ For any specific value $X = x$, $P(X = x) = 0$.

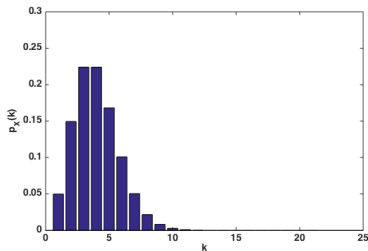
Examples might include:

- ▶ The time at which a bus arrives.
- ▶ The volume of water passing through a pipe over a given time period.
- ▶ The height of a randomly selected individual.

Probability mass function

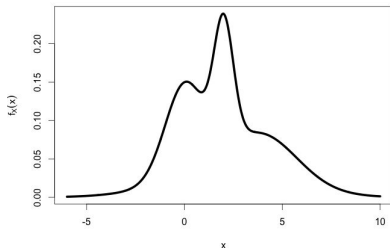
Remember for a discrete random variable X , we could describe the probability of X a particular value using the **probability mass function**.

- ▶ e.g. if $X \sim \text{Poisson}(\lambda)$, then the PMF of X is $p_X(k) = \frac{\lambda^k e^{-\lambda}}{k!}$
- ▶ We can read off the probability of a specific value of k from the PMF.
- ▶ We can use the PMF to calculate the **expected value** and the **variance** of X .
- ▶ We can plot the PMF using a histogram



Probability density function

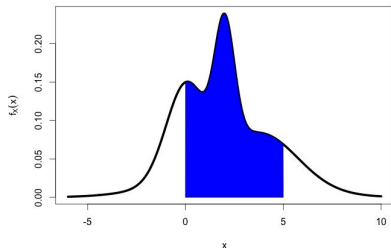
- ▶ For a continuous random variable, we cannot construct a PMF – each specific value has zero probability.
- ▶ Instead, we use a continuous, non-negative function $f_X(x)$ called the **probability density function**, or PDF, of X .



Probability density function

- ▶ For a continuous random variable, we cannot construct a PMF – each specific value has zero probability.
- ▶ Instead, we use a continuous, non-negative function $f_X(x)$ called the **probability density function**, or PDF, of X .
- ▶ The probability of X lying between two values x_1 and x_2 is simply the area under the PDF, i.e.

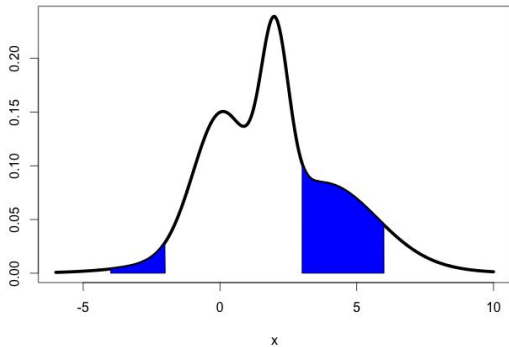
$$P(a \leq X \leq b) = \int_a^b f_X(x) dx$$



Probability density function

- ▶ More generally, for any subset B of the real line,

$$P(X \in B) = \int_B f_X(x) dx$$



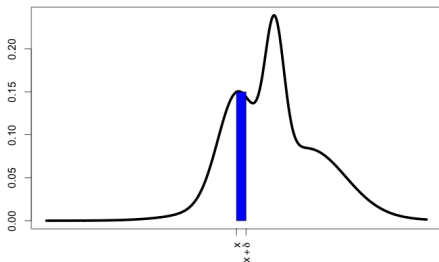
- ▶ Here, $B = (-4, -2) \cup (3, 6)$.

Properties of the pdf

- ▶ *Note that $f_X(a)$ is not $P(X = a)$!!*
- ▶ For any single value a , $P(X = a) = \int_a^a f_X(x)dx = 0$.
- ▶ This means that, for example,
 $P(X \leq a) = P(X < a) + P(X = a) = P(X < a)$.
- ▶ Recall that a valid probability law must satisfy $P(\Omega) = 1$ and $P(A) \geq 0$.
- ▶ f_X is non-negative, so $P(x \in B) = \int_{x \in B} f_X(x)dx \geq 0$ for all B
- ▶ To have normalization, we require,
 - ▶ $\int_{-\infty}^{\infty} f_X(x) = P(-\infty < X < \infty) = 1$ ← **total area under curve is 1.**
- ▶ Note that $f_X(x)$ can be greater than 1 – even infinite! – for certain values of x , provided the integral over all x is 1.

Intuition

- ▶ We can think of the probability of our random variable lying in some small interval of length δ , $[x, x + \delta]$
- ▶ $P(X \in [x, x + \delta]) = \int_x^{x+\delta} f_X(t) dt \approx f_X(x) \cdot \delta$



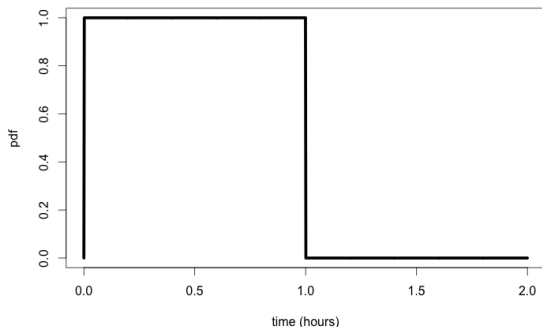
- ▶ Note however that $f_X(x)$ is **not** the probability at x .

Example: Continuous uniform random variable

- ▶ I know a bus is going to arrive some time in the next hour, but I don't know when. If I assume all times within that hour are equally likely, what will my PDF look like?

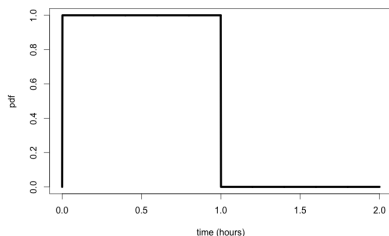
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$$f_X(x) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1 \\ 0 & \text{otherwise.} \end{cases}$$

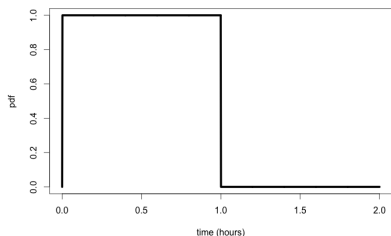
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$$f_X(x) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1 \\ 0 & \text{otherwise.} \end{cases}$$

- ▶ What is $P(X > 0.5)$?
- ▶ What is $P(X > 1.5)$?
- ▶ What is $P(X = 0.7)$?

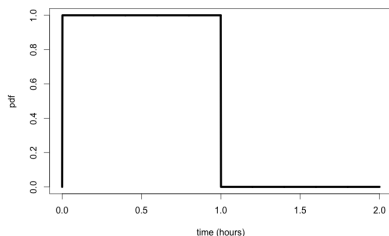
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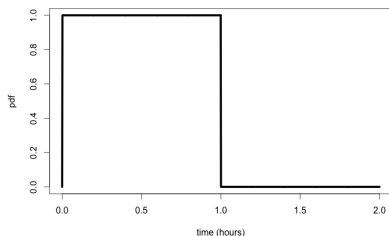
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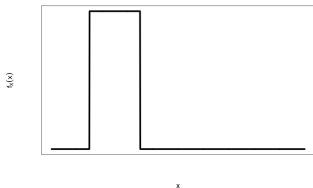
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- ▶ What is $P(X > 0.5)$? 0.5
- ▶ What is $P(X > 1.5)$? 0
- ▶ What is $P(X = 0.7)$? 0

Continuous uniform random variable

- ▶ More generally, X is a **continuous uniform random variable** if it has PDF

$$f_X(x) = \begin{cases} c & \text{if } a \leq x \leq b \\ 0 & \text{otherwise.} \end{cases}$$

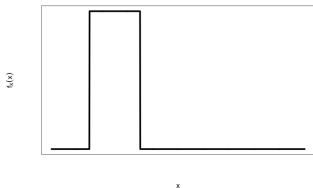


- ▶ What is c ?

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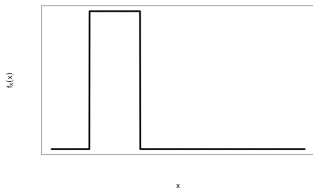
- ▶ What is c ?

- ▶ Well first lets see what $\int_a^b f_X(x) dx$ is!

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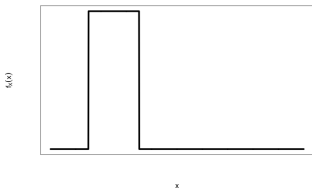
- ▶ What is c ?

- ▶ Well first lets see what $\int_a^b f_X(x) dx$ is!
- ▶ This is just the area under the curve, i.e. $(b - a) \times c \dots$

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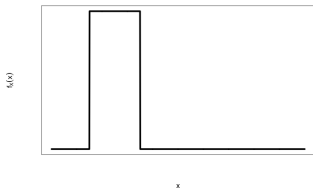
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- ▶ Well first lets see what $\int_a^b f_X(x)dx$ is!
- ▶ This is just the area under the curve, i.e. $(b - a) \times c \dots$
- ▶ But we want this to be 1. So c is

Continuous uniform random variable

- ▶ More generally, X is a **continuous uniform random variable** if it has PDF

$$f_X(x) = \begin{cases} c & \text{if } a \leq x \leq b \\ 0 & \text{otherwise.} \end{cases}$$



- ▶ What is c ?

- ▶ Well first lets see what $\int_a^b f_X(x)dx$ is!
- ▶ This is just the area under the curve, i.e. $(b - a) \times c \dots$
- ▶ But we want this to be 1. So c is $c = 1/(b - a)$

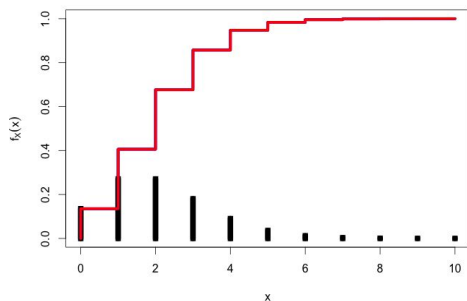
Cumulative distribution function

- ▶ Often we are interested in $P(X \leq x)$
- ▶ For example,
 - ▶ What is the probability that the bus arrives before 1:30?
 - ▶ What is the probability that a randomly selected person is under 5'7"?
 - ▶ What is the probability that this month's rainfall is less than 3in?
- ▶ We can get this from our PDF:

$$F_X(x) = P(X \leq x) = \begin{cases} \sum_{x' \leq x} p_X(x') & \text{if } X \text{ is a discrete r.v.} \\ \int_{-\infty}^x f_X(x') dx' & \text{if } X \text{ is a continuous r.v.} \end{cases}$$

- ▶ This is called the **cumulative distribution function** (CDF) of X .
- ▶ Note: If we know $P(X \leq x)$, we also know $P(X > x)$

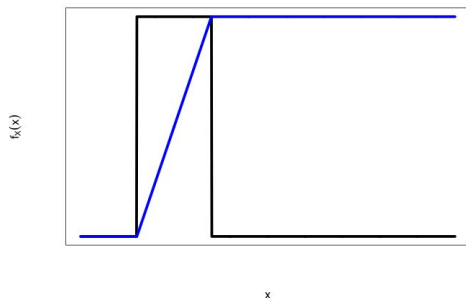
Cumulative distribution function



▶ If X is **discrete**, $F_X(x)$ is a piecewise-constant function of x .

▶
$$F_X(x) = \sum_{x' \leq x} p_X(x')$$

Cumulative distribution function

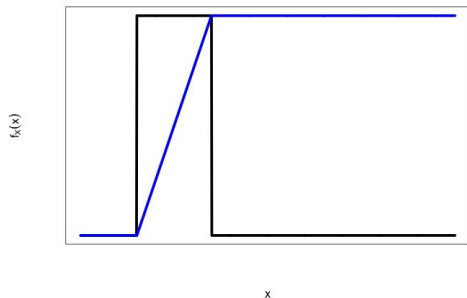


- ▶ The CDF is **monotonically non-decreasing**:

$$\text{if } x \leq y, \text{ then } F_X(x) \leq F_X(y)$$

- ▶ $F_X(x) \rightarrow 0$ as $x \rightarrow -\infty$
- ▶ $F_X(x) \rightarrow 1$ as $x \rightarrow \infty$

Cumulative distribution function



▶ If X is **continuous**, $F_X(x)$ is a continuous function of x

▶
$$F_X(x) = \int_{t=-\infty}^x f_X(t) dt$$

Expectation of a continuous random variable

- ▶ For discrete random variables, we found

$$E[X] = \sum_x xp_X(x)$$

- ▶ We can also think of the expectation of a continuous random variable – the number we would expect to get, on average, if we repeated our experiment infinitely many times.
- ▶ What do you think the expectation of a continuous random variable is?

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- ▶ What do you think the expectation of a continuous random variable is?
- ▶ $E[X] = \int_{-\infty}^{\infty} xf_X(x)dx$
- ▶ *Similar to the discrete case... but we are integrating rather than summing*
- ▶ Just as in the discrete case, we can think of $E[X]$ as the “center of gravity” of the PDF.

Expectation of functions of a continuous random variable

- ▶ What do you think the expectation of a function $g(X)$ of a continuous random variable is?

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- ▶ Note, $g(X)$ can be a continuous random variable, e.g. $g(X) = X^2$, or a discrete random variable, e.g.

$$g(X) = \begin{cases} 1 & \text{if } X \geq 0 \\ 0 & \text{if } X < 0 \end{cases}$$

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- ▶ We can also use our results for expectations and variances of linear functions:

$$E[aX + b] = aE[X] + b$$

$$\text{var}(aX + b) = a^2\text{var}(X)$$

Mean of a uniform random variable

Let X be a uniform random variable over $[a, b]$. What is its expected value?

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To calculate the variance, we need to calculate the second moment:

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So, the variance is

$$\text{var}(X) = E[X^2] - E[X]^2 = \frac{a^2 + ab + b^2}{3} - \frac{(a+b)^2}{4} = \frac{(b-a)^2}{12}$$

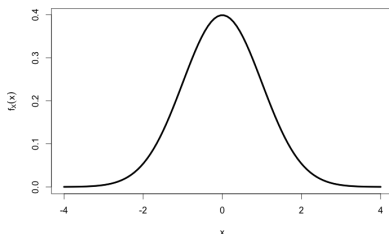
The normal distribution

- ▶ A normal, or Gaussian, random variable is a continuous random variable with PDF

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}$$

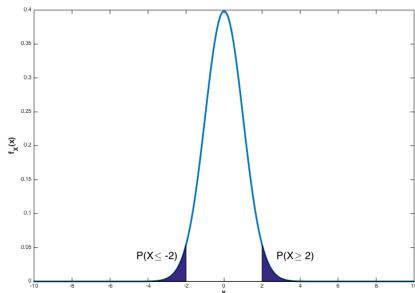
where μ and σ are scalars, and $\sigma > 0$.

- ▶ We write $X \sim N(\mu, \sigma^2)$.
- ▶ The mean of X is μ , and the variance is σ^2 (how could we show this?)



The normal distribution

- ▶ The normal distribution is the classic “bell-shaped curve”.
- ▶ It is a good approximation for a wide range of real-life phenomena.
 - ▶ Stock returns.
 - ▶ Molecular velocities.
 - ▶ Locations of projectiles aimed at a target.



- ▶ Further, it has a number of nice properties that make it easy to work with. Like symmetry. In the above picture, $P(X \geq 2) = P(X \leq -2)$.

Linear transformations of normal distributions

- ▶ Let $X \sim N(\mu, \sigma^2)$
- ▶ Let $Y = aX + b$
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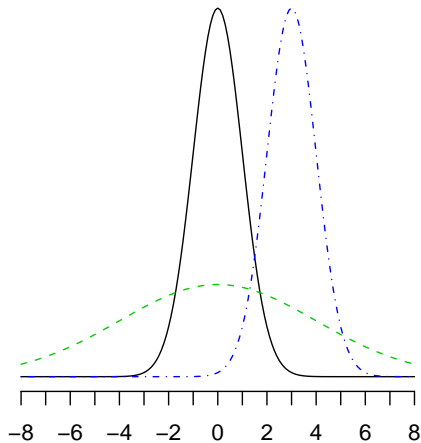
Linear transformations of normal distributions

- ▶ Let $X \sim N(\mu, \sigma^2)$
 - ▶ Let $Y = aX + b$
 - ▶ What are the mean and variance of Y ?
 - ▶ $E[Y] = a\mu + b$
 - ▶ $\text{var}[Y] = a^2\sigma^2$.
- ▶ In fact, if $Y = aX + b$, then Y is *also* a normal random variable, with mean $a\mu + b$ and variance $a^2\sigma^2$:

$$Y \sim N(a\mu + b, a^2\sigma^2)$$

The normal distribution

- ▶ **Example:** Below are the pdfs of $X_1 \sim N(0, 1)$, $X_2 \sim N(3, 1)$, and $X_3 \sim N(0, 16)$.
- ▶ Which pdf goes with which X ?



The standard normal

- ▶ I tell you that, if $X \sim N(0, 1)$, then $P(X < -1) = 0.159$.
- ▶ If $Y \sim N(1, 1)$, what is $P(Y < 0)$?
- ▶ Well we need to use the table of the **Standard Normal**.
- ▶ How do I transform Y such that it has the standard normal distribution?
- ▶ We know that a linear function of a normal random variable is also normally distributed!

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- ▶ So $P(Y < 0) = P(Z - 1 < -1) = P(X < -1) = 0.159$.

The standard normal

- ▶ If $Y \sim N(0, 4)$, what value of y satisfies $P(Y < y) = 0.159$?
- ▶ The variance of Y is 4 times that of a standard normal random variable.
- ▶ Transform into a $N(0, 1)$ random variable!

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- ▶ So $y/2 = -1$ and as a result $y = -2$...!

The standard normal

- ▶ It is often helpful to map our normal distribution with mean μ and variance σ^2 onto a normal distribution with mean 0 and variance 1.
- ▶ This is known as the **standard normal**
- ▶ If we know probabilities associated with the standard normal, we can use these to calculate probabilities associated with normal random variables with arbitrary mean and variance.
- ▶ If $X \sim N(\mu, \sigma^2)$, then $Z = \frac{X - \mu}{\sigma} \sim N(0, 1)$.
- ▶ (Note, we often use the letter Z for standard normal random variables)

The standard normal

- ▶ The CDF of the standard normal is denoted Φ :

$$\Phi(z) = P(Z \leq z) = P(Z < z) = \frac{1}{\sqrt{(2\pi)}} \int_{-\infty}^z e^{-t^2/2} dt$$

- ▶ We cannot calculate this analytically.
- ▶ The **standard normal table** lets us look up values of $\Phi(y)$.

	.00	.01	.02	0.03	0.04	...
0.0	0.5000	0.5040	0.5080	0.5120	0.5160	...
0.1	0.5398	0.5438	0.5478	0.5517	0.5557	...
0.2	0.5793	0.5832	0.5871	0.5910	0.5948	...
0.3	0.6179	0.6217	0.6255	0.6293	0.6331	...
⋮	⋮	⋮	⋮	⋮	⋮	

$$P(Z < 0.21) = 0.5832$$

CDF of a normal random variable

If $X \sim N(3, 4)$, what is $P(X < 0)$?

- ▶ First we need to **standardize**:

$$Z = \frac{X - \mu}{\sigma} = \frac{X - 3}{2}$$

- ▶ So, a value of $x = 0$ corresponds to a value of $z = -1.5$
- ▶ Now, we can translate our question into the standard normal:

$$P(X < 0) = P(Z < -1.5) = P(Z \leq -1.5)$$

- ▶ Problem... our table only gives $\Phi(z) = P(Z \leq z)$ for $z \geq 0$.

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- ▶ But, $P(Z \geq 1.5) = 1 - P(Z < 1.5) = 1 - P(Z \leq 1.5) = 1 - \Phi(1.5)$.
- ▶ And we're done!
 $P(X < 0) = 1 - \Phi(1.5) = (\text{look at the table...})1 - 0.9332 = 0.0668$

Recap

- ▶ With continuous random variables, any specific value of $X = x$ has zero probability.
- ▶ So, writing a function for $P(X = x)$ – like we did with discrete random variables – is pretty pointless.
- ▶ Instead, we work with **PDFs** $f_X(x)$ – functions that we can integrate over to get the probabilities we need.

$$P(X \in B) = \int_B f_X(x) dx$$

- ▶ We can think of the PDF $f_X(x)$ as the “probability mass per unit area” near x .
- ▶ We are often interested in the probability of $X \leq x$ for some x – we call this the cumulative distribution function $F_X(x) = P(X \leq x)$.
- ▶ Once we know $f_X(x)$, we can calculate expectations and variances of X .